

Current Projects



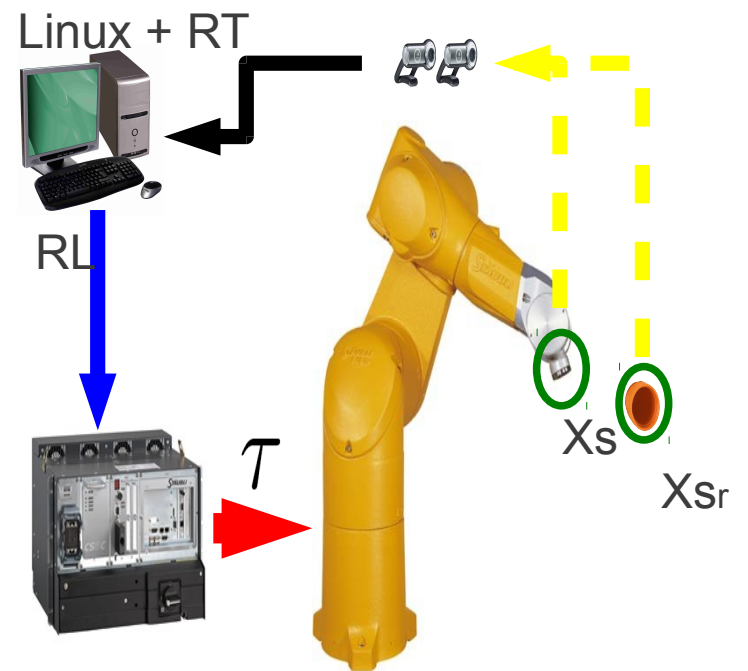
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Robotics and Embedded Systems
TUM

Robot Control

Closed Architecture Robot Systems



Open Architecture Robot Systems



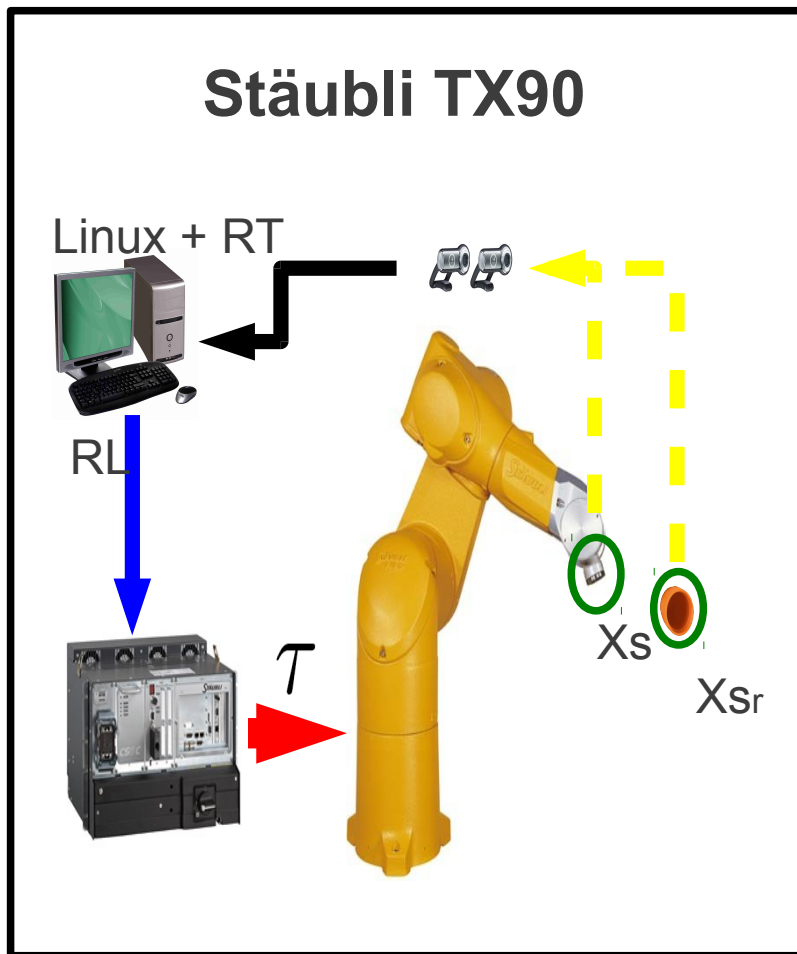
Closed Architecture Robot System

JAHIR



- ◆ Model-based observers.
- ◆ Sensorless impedance control. (Claus)
- ◆ Matlab Robot-Modeler Tool Box.
- ◆ OpenTL Hough Lines Modality (Giorgio)

Open Architecture Robot System



- ◆ Control Design and Implementation
- ◆ Dynamical Visual Servoing (Suraj)
- ◆ Dynamic Compensation Control (Suraj)

That's all folks!!!!!!